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Design and simplified calibration of a Mueller imaging polarimeter for material classification

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This study is concerned with the design of a Mueller imaging polarimeter for the visualization of spatially-varying Mueller matrix fields. A simplified calibration procedure is advocated, where all the optical elements are calibrated simultaneously rather than independently as in the state-of-the-art. This is shown to significantly reduce the bias inherent to sequential calibration methods. In addition, this procedure requires no reference sample, it allows calibration both in transmission or in reflection modes, and it relies on ready-to-use cameras. Put together, these novelties should help non-specialists in optics designing and calibrating a Mueller imaging polarimeter for applications such as material classification. © 2019 Optical Society of America. One print or electronic copy may be made for personal use only. Systematic reproduction and distribution, duplication of any material in this paper for a fee or for commercial purposes, or modifications of the content of this paper are prohibited.

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The polarization properties of a medium can be measured through Mueller polarimetry [1], and have proven to be of fundamental importance in many applications such as biomedical diagnosis [2] or material classification [3]. Although the design and calibration of a Mueller polarimeter has long been investigated in the Optics community, most of existing works focus on the accurate measure of a single Mueller matrix, using e.g. a HgCdTe photodetector [4] or a photodiode [5]. On the other hand, practitioners need two-dimensional visualizations of the Mueller matrix field, in order to identify spatially-varying properties. Yet, non-specialists in Optics would probably favor a solution based on commercial cameras, which requires no reference sample [6] or post-processing to remove calibration errors [7–10], and which can handle both transmission and reflection modes [11]. Calibration procedures that meet such requirements do already exist [5, 12] but they consider a dedicated calibration procedure for each optical element. One objective of this study is to show that one should rather simultaneously calibrate all the optical elements, for the sake of both simplicity and accuracy. Overall, this results in an easy-to-implement calibration procedure which simultaneously meets all the aforementioned requirements, and should hopefully help non-specialists in Optics in the design of a Mueller imaging polarimeter.

Fig. 1. Polarimeter used in our experiments, comprising a Kohler illumination (blue), a PSG (cyan) consisting of a polarizer $P^G$ and a retarder $R^G$, a medium $M$ to be analyzed (white), a PSA (yellow) consisting of a retarder $R^A$ and a polarizer $P^A$, and a CCD camera with interference filters (red).

We consider a dual-rotating Mueller polarimeter composed of the following elements, from source to detector (see Figure 1):

• A Kohler illumination system emitting a parallel and uniform white lighting;
• A polarization state generator (PSG) comprising:
  – a linear polarizer $P^G$ with angle $\theta^G$;
  – a retarder $R^G$ with controllable fast axis (azimuth) $\alpha^G$;
• A medium $M$ to be analyzed;
• A polarization state analyzer (PSA) comprising:
  – a retarder $R^A$ with controllable azimuth $\alpha^A$;
  – a linear polarizer $P^A$ with angle $\theta^A$;
• A CCD camera equipped with interference filters.1

In dual-rotating Mueller polarimetry [11–14], both polarizers are kept fixed while several images are acquired under varying azimuthal angles of the retarders. The optical properties of the medium, represented by its Mueller matrix $M$, can be obtained by solving a system of equations having the following form:

$$\begin{bmatrix} I & Q & U & V \end{bmatrix}^T \propto P^A R^A M R^G P^G \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^T,$$

where $[I, 0, 0, 0]^T$ is the Stokes vector of the (unpolarized) light entering the PSG, the Ihs is the Stokes vector of the (polarized) light entering the detector, with $I$ the intensity measured by the camera, and the Mueller matrices in the rhs are given the same name as the optical element they represent.

1In our experiments, we used Newport 10LP-VIS-B polarizers and Newport 10BWP4-532 zero-order waveplates, with a Stingray F-033B graylevel camera, Newport 10BPF10 band-pass filters and Newport AG-PR300F piezo rotation stages to control the angles from 0° to 340° with a resolution of 0.001°.
We first describe a sequential calibration procedure where the polarimeter is calibrated using Levenberg-Marquardt's algorithm \cite{16}.

To calibrate the PSG retarder, the PSA retarder is removed \((R^A = I_4)\), and the angles of both polarizers are set to zero \((\theta^G = \theta^0_G \text{ and } \theta^A = \theta^0_A)\). The unknowns are the angle \(\alpha^G_n\) and the delay \(\delta^G_i\) (which is a function of the wavelength). To estimate them, we take \(m\) series of shots under different wavelength \(\lambda^i, i \in \{1, \ldots, m\}\), and for each series \(i\) we record \(n\) measurements \(I^k_i, k \in \{1, \ldots, n\}\) under varying angle \(\phi^G_k, \delta^G_i\), \(k \in \{1, \ldots, n\}\). Let us assume again homoskedastic, zero-mean Gaussian noise, and denote by \(b^i\) the proportionality constant (which is wavelength-dependent, due to the sensor response being wavelength-dependent) and by \(\delta^G_i\) the delay for the wavelength \(\lambda^i\). By expanding the first row of Eq. (1) along with Eq. (2) and Eq. (3), the maximum likelihood estimation for the set of unknown parameters \(\{\alpha^G_n, \{b^i, \delta^G_i\}_{i \in \{1, \ldots, m\}}\}\) is attained by solving the following nonlinear least-squares problem using, e.g., Levenberg-Marquardt’s algorithm:

\[
\min_{\alpha^G_n, \{b^i, \delta^G_i\}} \sum_{i=1}^m \sum_{k=1}^n \left( b^i \left( \frac{2 + \cos \delta^G_i - 1}{2} \right) \frac{\sin^2(2(\alpha^G_n - \alpha^0_n) - k^i)}{k^i} \right)^2 \tag{5}
\]

Then, from the estimated values \(\{\alpha^G_n\}_i\) of the delays we can obtain the delay value for any wavelength \(\lambda\) according to Cauchy’s approximation\footnote{This can be accomplished either by using a multispectral camera, or by placing narrow-band interference filters before a monochromatic CCD sensor.}:

\[
\delta^G_0(\lambda) = \frac{k^G_1}{\lambda} + \frac{k^G_2}{\lambda^2}, \tag{6}
\]

where \(k^G_1, k^G_2\) can be obtained by solving in a least-squares manner the system of linear equations formed by the \(m\) equations (6) with the estimated values \(\{\delta^G_0_i\}\) and the chosen wavelengths \(\{\lambda^i\}\). Columns two to four in Figure 2 show examples of results for the calibration of the PSG and PSA retarders of Figure 1 (the calibration procedure for the PSA retarder is exactly the same as that of the PSG, provided that the angle of the PSG retarder is set to zero i.e., \(\alpha^G = \alpha^0_G\)).

B. Bundle-adjusted polarimeter calibration

Given the sequential nature of the previous approach, bias may be accumulated through the procedure (e.g., a wrong calibration of the PSA polarizer will bias the calibration of the PSG retarder, and that of the PSA retarder even more). Moreover, slight displacements of the optical elements between the numerous steps may be another source of bias. Therefore, an integrated calibration method for the joint estimation of all parameters (the three angles \(\theta^A, \alpha^G, \alpha^0_G\), and \(\theta^0_A\), and the four parameters \(k^G_1, k^G_2\) of the two delay functions \(\delta^G_i/A\) modeled as in Eq. (6)) would require less manual intervention, and be more accurate. We now introduce such a method, which is inspired by the classic bundle adjustment method widely used in computer vision \cite{17}.

Let us consider a series of measurements \(I^k_i\) obtained under varying wavelength \(\{\lambda^i\}\), polarizer angle \(\{\theta^A_i\}_i\), PSG azimuth \(\{\alpha^G_i\}_i\) and PSA azimuth \(\{\lambda^i A\}_i\) \footnote{We used Cauchy’s approximation since we focus on the visible spectrum, yet a more accurate model such as Sellmeier’s could have been employed.}, and 8 different values for the angles taken every 22.5° between 0° and 157.5° for the azimuths \(\alpha^G_i/A\), and every 45° between 0° and 315° for the polarizer angles \(\alpha^0_G\).
Let us assume that Eq. (1) is satisfied up to additive, zero-mean and homoskedastic Gaussian noise, and denote by $b_i$ the unknown scale parameter for the $i$-th wavelength. The maximum likelihood estimate for the set of unknown parameters is thus attained by solving the nonlinear least-squares problem

$$
\min_{a^0_i, k^1_i, k^2_i, \theta^0_i} \sum_{i,j} \left( b_i^T \left( A_i^j(a^0_i, k^1_i, k^2_i, \theta^0_i) + \kappa G_i^j(a^0_i, k^1_i, k^2_i) - \hat{I}_i^j \right) \right)^2
$$

with $I_i^j$ the first row of the PSA matrix $A$ in Eq. (1) given, according to Eq. (2), Eq. (3) and Eq. (6), by

$$
I_i^j(a^0_i, k^1_i, k^2_i, \theta^0_i) = \begin{eqnarray}
\cos^2 (\frac{\theta^0_i - \theta^0_j}{2}) & \cos^2 (\frac{\theta^0_i + \theta^0_j}{2}) + \cos \left( \frac{\theta^0_i - \theta^0_j}{2} \right) \sin \left( \frac{\theta^0_i - \theta^0_j}{2} \right) & \cos^2 (\frac{\theta^0_i - \theta^0_j}{2}) \sin \left( \frac{\theta^0_i - \theta^0_j}{2} \right) \sin \left( \frac{\theta^0_i + \theta^0_j}{2} \right) \\
\sin^2 (\frac{\theta^0_i - \theta^0_j}{2}) & \sin^2 (\frac{\theta^0_i + \theta^0_j}{2}) + \cos \left( \frac{\theta^0_i - \theta^0_j}{2} \right) \sin \left( \frac{\theta^0_i - \theta^0_j}{2} \right) & \sin^2 (\frac{\theta^0_i - \theta^0_j}{2}) \sin \left( \frac{\theta^0_i - \theta^0_j}{2} \right) \sin \left( \frac{\theta^0_i + \theta^0_j}{2} \right) \\
\sin^2 (\frac{\theta^0_i - \theta^0_j}{2}) & \sin^2 (\frac{\theta^0_i + \theta^0_j}{2}) + \cos \left( \frac{\theta^0_i - \theta^0_j}{2} \right) \sin \left( \frac{\theta^0_i - \theta^0_j}{2} \right) & \sin^2 (\frac{\theta^0_i - \theta^0_j}{2}) \sin \left( \frac{\theta^0_i - \theta^0_j}{2} \right) \sin \left( \frac{\theta^0_i + \theta^0_j}{2} \right) \\
\sin^2 (\frac{\theta^0_i - \theta^0_j}{2}) & \sin^2 (\frac{\theta^0_i + \theta^0_j}{2}) + \cos \left( \frac{\theta^0_i - \theta^0_j}{2} \right) \sin \left( \frac{\theta^0_i - \theta^0_j}{2} \right) & \sin^2 (\frac{\theta^0_i - \theta^0_j}{2}) \sin \left( \frac{\theta^0_i - \theta^0_j}{2} \right) \sin \left( \frac{\theta^0_i + \theta^0_j}{2} \right)
\end{eqnarray}
$$

and $G_i^j$ the Stokes vector exiting the PSG given, according to Eq. (2), Eq. (3) and Eq. (6), by

$$
\kappa G_i^j(a^0_i, k^1_i, k^2_i) = \begin{eqnarray}
\left[ \cos \left( \frac{\theta^0_i + \theta^0_j}{2} \right) \sin \left( \frac{\theta^0_i - \theta^0_j}{2} \right) + \cos \left( \frac{\theta^0_i + \theta^0_j}{2} \right) \sin \left( \frac{\theta^0_i - \theta^0_j}{2} \right) \right] \\
\left[ \left( 1 - \cos \left( \frac{\theta^0_i + \theta^0_j}{2} \right) \right) \cos \left( \frac{\theta^0_i - \theta^0_j}{2} \right) \sin \left( \frac{\theta^0_i - \theta^0_j}{2} \right) + \cos \left( \frac{\theta^0_i + \theta^0_j}{2} \right) \sin \left( \frac{\theta^0_i - \theta^0_j}{2} \right) \right] \\
\left[ - \sin \left( \frac{\theta^0_i + \theta^0_j}{2} \right) \sin \left( \frac{\theta^0_i - \theta^0_j}{2} \right) \sin \left( \frac{\theta^0_i - \theta^0_j}{2} \right) \cos \left( \frac{\theta^0_i - \theta^0_j}{2} \right) \right] \\
\left[ - \sin \left( \frac{\theta^0_i + \theta^0_j}{2} \right) \sin \left( \frac{\theta^0_i - \theta^0_j}{2} \right) \sin \left( \frac{\theta^0_i - \theta^0_j}{2} \right) \cos \left( \frac{\theta^0_i - \theta^0_j}{2} \right) \right]
\end{eqnarray}
$$

The angles estimated with this integrated approach differ by less than $2^\circ$ from those obtained with the sequential approach, thus we do not reproduce any new calibration result. It is the computation of real-world Mueller matrix measurements which will highlight the significance of this slight difference. Still, we already remark that in the sequential procedure, we used a total of $3 \times 3400 = 10200$ observations per wavelength. In contrast, we used 20 times less (512 per wavelength) observations for the bundle-adjusted method: if the latter is to provide similar results with so much fewer observations then it can be considered as substantially better in terms of simplicity.

C. Polarimetric Imaging

To measure real-world Mueller matrices, the polarizers are aligned ($\theta^A = \theta^0$ and $\theta^G = \theta^0$) and the two retarders are controlled through their azimuth $a^G := a^G - a^0$ and $a^A := a^A - a^0$.

The first row in Eq. (1) then turns into the following linear equation in the 16 unknown coefficients of matrix $M$:

$$
I(a^A, a^G) = \begin{bmatrix}
1 \\
1 - \cos (\frac{\theta^0}{2}) \sin^2 \left( \frac{\theta^0}{2} \right) + \sin (\frac{\theta^0}{2}) \cos (\frac{\theta^0}{2}) \\
\sin (\frac{\theta^0}{2}) \cos (\frac{\theta^0}{2}) \\
1 - \cos (\frac{\theta^0}{2}) \sin^2 \left( \frac{\theta^0}{2} \right) - \sin (\frac{\theta^0}{2}) \cos (\frac{\theta^0}{2}) \\
\sin (\frac{\theta^0}{2}) \cos (\frac{\theta^0}{2})
\end{bmatrix} M
$$

We acquire $m$ series of intensity measurements under varying PSA retarder angle $a^A$. In each series, we acquire $n$ measurements under varying PSG retarder angle $a^G$. The resulting $mn$ observations then allow the system of $mn$ equations such as Eq. (10) to be solved in the least-squares sense.

Our piezo rotating stages being limited to a speed of 1.5 /sec., in our experiments it takes around 1.5 hrs to acquire the 512 measurements used to calibrate the polarimeter at one particular wavelength, and around 10 min to acquire the 64 ones used for polarimetric imaging. These numbers might be significantly reduced by using faster rotating stages.

We used $m = n = 8$ angles equally spaced between $0^\circ$ and $157.5^\circ$. This yields conditioning numbers of 3.39 and 3.99 for the 64 x 4 matrices $A$ and $G$ in Eq. (10). These values are exactly the same as those associated with the theoretically optimal [6] set of 64 angles obtained with synchronous variations of both azimuths at a 1:3 speed ratio.
We first calibrated the polarimeter in transmission mode and then estimated the Mueller matrix\textsuperscript{9} of the air at 540 nm (the expected result is the matrix $M_{\text{air}}^{\text{trans}}$ equal to identity). Then we calibrated it again in reflection mode and estimated the Mueller matrix of a mirror at 540 nm (the expected result is a diagonal matrix $M_{\text{mirr}}^{\text{mirr}}$ with non-zero elements $[1, 1, -1, -1]^\top$). The results shown in Table 1 show that the bundle-adjusted calibration method significantly reduces errors. The spatial uniformity of the error distribution further suggests that the remaining errors are mostly due to the accuracy of the detector.

Figure 3 illustrates the ability of the discussed polarimeter, calibrated in reflection mode, to reconstruct spatially-varying Mueller matrix fields. In this experiment the scene contains three objects whose material can hardly be discriminated from the graylevel image (see the top-left image), but visualization of the Mueller matrix coefficients (for instance, $M_{22}$ and $M_{43}$) makes this task straightforward. This shows the potential of the proposed simplified calibration procedure for Mueller polarimeters in material classification.

### REFERENCES


### Table 1

Estimated Mueller matrices and relative error for the air (transmission mode, first row) and a mirror (reflection mode, second row), using the calibration parameters obtained with the sequential (left) and bundle-adjusted methods (right). The bottom figures show the spatial distribution of errors for the mirror, in false colors (blue is zero, yellow is 0.04).

<table>
<thead>
<tr>
<th>$M_{\text{air}}^{\text{seq}}$</th>
<th>$|M_{\text{air}}^{\text{seq}} - M_{\text{air}}^{\text{mirr}}|_F$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\begin{bmatrix} 1.000 &amp; 0.001 &amp; 0.004 &amp; 0.003 \ 0.002 &amp; 0.997 &amp; -0.015 &amp; 0.009 \ -0.007 &amp; 0.001 &amp; 0.992 &amp; -0.004 \ 0.001 &amp; -0.005 &amp; -0.001 &amp; 0.997 \end{bmatrix}$</td>
<td>0.015</td>
</tr>
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<table>
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<tr>
<th>$M_{\text{mirr}}^{\text{seq}}$</th>
<th>$|M_{\text{mirr}}^{\text{seq}} - M_{\text{mirr}}^{\text{mirr}}|_F$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\begin{bmatrix} 1.000 &amp; -0.007 &amp; 0.003 &amp; -0.003 \ -0.007 &amp; 1.002 &amp; -0.010 &amp; 0.011 \ -0.007 &amp; 0.007 &amp; 1.005 &amp; -0.002 \ 0.003 &amp; -0.002 &amp; 0.003 &amp; 0.996 \end{bmatrix}$</td>
<td>0.011</td>
</tr>
</tbody>
</table>

Fig. 3. Estimated field of Mueller matrices for a scene containing two wooden objects (top) and a rubber (bottom). The diagonal elements clearly discriminate rubber from wood, while the two types of wood are easily discriminated using $M_{43}$. 
FULL REFERENCES


